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PART I: Mechanics of Rigid Bodies

Chapter 1

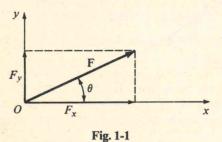
Properties of Forces and Force Systems

COMPONENTS OF A FORCE

The components (or scalar components) of a force F in the x and y directions are denoted by F_x and F_y , respectively (Fig. 1-1), and are

$$F_{x} = |\mathbf{F}| \cos \theta \qquad F_{y} = |\mathbf{F}| \sin \theta \qquad (1.1)$$

where the vertical bars denote the magnitude of the vector F.



A

Fig. 1-2

VECTOR ADDITION

Two vectors \mathbf{A} and \mathbf{B} may be added by taking \mathbf{A} and \mathbf{B} as adjacent sides of a parallelogram, as indicated in Fig. 1-2. The vector sum (or *resultant*) of \mathbf{A} and \mathbf{B} is then the vector from the origin of \mathbf{A} and \mathbf{B} along the diagonal to the opposite corner. This defines the *parallelogram rule* for vector addition. We sometimes refer to \mathbf{A} and \mathbf{B} of Fig. 1-2 as vector components of $\mathbf{A} + \mathbf{B}$.

DOT PRODUCT

The dot product (or scalar product) of two vectors \mathbf{A} and \mathbf{B} is the product of the magnitudes of the two vectors multiplied by the cosine of the acute angle α between them, as shown in Fig. 1-3:

$$\mathbf{A} \cdot \mathbf{B} = |\mathbf{A}| |\mathbf{B}| \cos \alpha \tag{1.2}$$

It is frequently convenient to work with unit vectors (i.e., vectors of unit length) directed along the x, y, and z axes, as shown in Fig. 1-4. These are denoted i, j, and k, respectively. From (1.2) we obviously have

$$\mathbf{i} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{j} = \mathbf{k} \cdot \mathbf{k} = 1$$

$$\mathbf{i} \cdot \mathbf{j} = \mathbf{j} \cdot \mathbf{k} = \mathbf{i} \cdot \mathbf{k} = 0$$
(1.3)

Figure 1-5 shows the extension of these ideas to three-dimensional space.