

Contents

Preface	xi
1 Introduction	1
1.1 One-dimensional inverse kinematics problem	3
1.2 Inverse dynamical problem for a string	8
1.3 Inverse problems for a layered medium	16
2 Ray statements of inverse problems	19
2.1 Posing of the inverse problems	19
2.2 Asymptotic expansion	21
2.2.1 Asymptotic expansion of the solution	21
2.2.2 Reduction of the inverse problem	23
2.2.3 Construction of $\tau(x, y)$	24
2.2.4 Proof of the expansion in the odd-dimensional case . .	27
2.2.5 Proof of the expansion in the even-dimensional case .	33
2.2.6 Proof of the auxiliary lemma	35
2.3 Uniqueness theorems for the inverse problem	38
2.3.1 A proof of the stability estimate for the integral geometry problem	43
2.3.2 Uniqueness theorem for the integral geometry problem related to a vector field	53
2.3.3 Proof of the uniqueness theorem for inverse kinematics problem	59
2.3.4 The wave equation with an attenuation	61
2.3.5 Concluding remarks	62
2.4 Inverse problems related to a local heterogeneity	62
3 Local solvability of some inverse problems	69
3.1 Banach's spaces of analytic functions	70
3.2 Determining coefficients of the lower terms	71
3.2.1 Determining a coefficient of the lower term	71

3.2.2 Determining an attenuation coefficient	79
3.3 Determining the speed of the sound	82
3.4 A regularization method for solving an inverse problem	91
3.4.1 Theorems related to the system of integro-differential equations	95
3.4.2 Estimates of a solution to the algebraic equations	102
3.4.3 Convergence the approximate solution to the exact one	110
4 Inverse problems with single measurements	121
4.1 Determining coefficient of the lowest term	122
4.1.1 Statement of the problem and stability estimates	122
4.1.2 Proof of the stability theorems	124
4.1.3 Proof of Lemma 4.1.3	126
4.1.4 Proof of Lemma 4.1.4	130
4.2 Determining coefficients under first derivatives	136
4.3 Determining the speed of sound in the wave equation	141
4.3.1 Formulation of the problem and a stability estimate of the solution	142
4.3.2 Proof of Theorem 4.3.1	144
4.3.3 Proof of Lemma 4.3.5	150
4.3.4 Proof of Lemma 4.3.6	155
4.3.5 Proof of the inequality (4.3.24)	162
4.4 Case of a point source	162
4.4.1 Formulations of the problem and results	163
4.4.2 Proofs of the stability theorems	164
4.4.3 Properties of a solution to problem (4.4.1)	167
4.4.4 Proof of Lemma 4.4.3	168
4.4.5 Proof of Lemma 4.4.4	170
5 Stability estimates related to inverse problems for the transport equation	175
5.1 The problem of determining the relaxation and a density of inner sources	176
5.1.1 Statement of basic and auxiliary problems	176
5.1.2 The basic results	179
5.1.3 Proof of Theorem 5.1.1	187
5.1.4 Proof of the auxiliary lemmas	194
5.2 A stability estimate in the problem of determining the dispersion index and relaxation in 2D	201
5.2.1 Statement of the problem and the basic results	202
5.2.2 Proof of Lemma 5.2.1	206

5.2.3	A priori estimates	208
5.2.4	Proof of Theorem 5.2.3	221
5.3	The problem of determining the dispersion index and relaxation in 3D	224
5.3.1	Statement of the problem and the main results	224
5.3.2	Proof of Lemma 5.3.1	230
5.3.3	A priori estimates for function $w(x, \nu)$	232
5.3.4	Estimates for functions $\bar{w}(x, \nu)$ and $\tilde{\sigma}(x)$	234
5.3.5	A priori estimates and differential properties of function $\bar{u}(x, \nu, \nu^0)$	238
5.3.6	A priori estimates and properties of function $v(x, \nu, \nu^0)$	241
5.3.7	Equations for the derivatives of function $\tilde{v}(x, \nu, \nu^0)$. .	243
5.3.8	Proof of inequality (5.3.24)	249
5.3.9	Proof of inequality (5.3.25)	251
5.3.10	Proof of inequality (5.3.26)	254
5.3.11	Auxiliary formulae	256
Bibliography		262