Graduate Texts in Mathematics 195

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Melvyn B. Nathanson

Elementary Methods in Number Theory

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To Paul Erdős,

1913–1996,

a friend and collaborator for 25 years, and a master of elementary methods in number theory.

Preface

Arithmetic is where numbers run across your mind looking for the answer.

Arithmetic is like numbers spinning in your head faster and faster until you blow up with the answer.

KABOOM!!!

Then you sit back down and begin the next problem.

Alexander Nathanson [99]

This book, *Elementary Methods in Number Theory*, is divided into three parts.

Part I, "A first course in number theory," is a basic introduction to elementary number theory for undergraduate and graduate students with no previous knowledge of the subject. The only prerequisites are a little calculus and algebra, and the imagination and perseverance to follow a mathematical argument. The main topics are divisibility and congruences. We prove Gauss's law of quadratic reciprocity, and we determine the moduli for which primitive roots exist. There is an introduction to Fourier analysis on finite abelian groups, with applications to Gauss sums. A chapter is devoted to the abc *conjecture*, a simply stated but profound assertion about the relationship between the additive and multiplicative properties of integers that is a major unsolved problem in number theory.

The "first course" contains all of the results in number theory that are needed to understand the author's graduate texts, *Additive Number Theory: The Classical Bases* [104] and *Additive Number Theory: Inverse Problems and the Geometry of Sumsets* [103].

The second and third parts of this book are more difficult than the "first course," and require an undergraduate course in advanced calculus or real analysis.

Part II is concerned with prime numbers, divisors, and other topics in multiplicative number theory. After deriving properties of the basic arithmetic functions, we obtain important results about divisor functions, and we prove the classical theorems of Chebyshev and Mertens on the distribution of prime numbers. Finally, we give elementary proofs of two of the most famous results in mathematics, the *prime number theorem*, which states that the number of primes up to x is asymptotically equal to $x/\log x$, and *Dirichlet's theorem* on the infinitude of primes in arithmetic progressions.

Part III, "Three problems in additive number theory," is an introduction to some classical problems about the additive structure of the integers. The first additive problem is *Waring's problem*, the statement that, for every integer $k > 2$, every nonnegative integer can be represented as the sum of a bounded number of kth powers. More generally, let $f(x) = a_k x^k +$ $a_{k-1}x^{k-1} + \cdots + a_0$ be an integer-valued polynomial with $a_k > 0$ such that the integers in the set $A(f) = \{f(x) : x = 0, 1, 2, \ldots\}$ have no common divisor greater than one. Waring's problem for polynomials states that every sufficiently large integer can be represented as the sum of a bounded number of elements of $A(f)$.

The second additive problem is *sums of squares*. For every $s \geq 1$ we denote by $R_s(n)$ the number of representations of the integer n as a sum of s squares, that is, the number of solutions of the equation

$$
n = x_1^2 + \dots + x_s^2
$$

in integers x_1, \ldots, x_s . The shape of the function $R_s(n)$ depends on the parity of s. In this book we derive formulae for $R_s(n)$ for certain even values of s, in particular, for $s = 2, 4, 6, 8$, and 10.

The third additive problem is the *asymptotics of partition functions*. A partition of a positive integer n is a representation of n in the form $n = a_1 + \cdots + a_k$, where the parts a_1, \ldots, a_k are positive integers and $a_1 \geq \cdots \geq a_k$. The partition function $p(n)$ counts the number of partitions of *n*. More generally, if A is any nonempty set of positive integers, the partition function $p_A(n)$ counts the number of partitions of n with parts belonging to the set A. We shall determine the asymptotic growth of $p(n)$ and, more generally, of $p_A(n)$ for any set A of integers of positive density.

This book contains many examples and exercises. By design, some of the exercises require old-fashioned manipulations and computations with pencil and paper. A few exercises require a calculator. Number theory, after all, begins with the positive integers, and students should get to know and love them.

This book is also an introduction to the subject of "elementary methods in analytic number theory." The theorems in this book are simple statements about integers, but the standard proofs require contour integration,

modular functions, estimates of exponential sums, and other tools of complex analysis. This is not unfair. In mathematics, when we want to prove a theorem, we may use any method. The rule is "no holds barred." It is OK to use complex variables, algebraic geometry, cohomology theory, and the kitchen sink to obtain a proof. But once a theorem is proved, once we know that it is true, particularly if it is a simply stated and easily understood fact about the natural numbers, then we may want to find another proof, one that uses only "elementary arguments" from number theory. Elementary proofs are not better than other proofs, nor are they necessarily easy. Indeed, they are often technically difficult, but they do satisfy the aesthetic boundary condition that they use only arithmetic arguments.

This book contains elementary proofs of some deep results in number theory. We give the Erd˝os-Selberg proof of the prime number theorem, Linnik's solution of Waring's problem, Liouville's still mysterious method to obtain explicit formulae for the number of representations of an integer as the sum of an even number of squares, and Erdős's method to obtain asymptotic estimates for partition functions. Some of these proofs have not previously appeared in a text. Indeed, many results in this book are new.

Number theory is an ancient subject, but we still cannot answer the simplest and most natural questions about the integers. Important, easily stated, but still unsolved problems appear throughout the book. You should think about them and try to solve them.

> Melvyn B. Nathanson $¹$ </sup> Maplewood, New Jersey November 1, 1999

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Notation and Conventions

We denote the set of positive integers (also called the natural numbers) by **N** and the set of nonnegative integers by N_0 . The integer, rational, real, and complex numbers are denoted by **Z**, **Q**, **R**, and **C**, respectively. The absolute value of $z \in \mathbb{C}$ is |z|. We denote by \mathbb{Z}^n the group of lattice points in the *n*-dimensional Euclidean space \mathbb{R}^n .

The integer part of the real number x, denoted by $[x]$, is the largest integer that is less than or equal to x. The fractional part of x is denoted by $\{x\}$. Then $x = [x] + \{x\}$, where $[x] \in \mathbb{Z}$, $\{x\} \in \mathbb{R}$, and $0 \leq \{x\} < 1$. In computer science, the integer part of x is often called the *floor* of x, and denoted by $|x|$. The smallest integer that is greater than or equal to x is called the *ceiling* of x and denoted by $[x]$.

We adopt the standard convention that an empty sum of numbers is equal to 0 and an empty product is equal to 1. Similarly, an empty union of subsets of a set X is equal to the empty set, and an empty intersection is equal to X .

We denote the *cardinality* of the set X by |X|. The largest element in a finite set of numbers is denoted by $max(X)$ and the smallest is denoted by $min(X)$.

Let a and d be integers. We write d/a if d divides a, that is, if there exists an integer q such that $a = dq$. The integers a and b are called *congruent* modulo m, denoted by $a \equiv b \pmod{m}$, if m divides $a - b$.

A *prime number* is an integer $p > 1$ whose only divisors are 1 and p. The set of prime numbers is denoted by P , and p_k is the kth prime. Thus, $p_1 = 2, p_2 = 3, \ldots, p_{11} = 31, \ldots$ Let p be a prime number. We write $p^r || n$ if p^r is the largest power of p that divides the integer n, that is, p^r divides *n* but p^{r+1} does not divide *n*.

The *greatest common divisor* and the *least common multiple* of the integers a_1, \ldots, a_k are denoted by (a_1, \ldots, a_k) and $[a_1, \ldots, a_k]$, respectively. If A is a nonempty set of integers, then $gcd(A)$ denotes the greatest common divisor of the elements of A.

The *principle of mathematical induction* states that if $S(k)$ is some statement about integers $k \geq k_0$ such that $S(k_0)$ is true and such that the truth of $S(k-1)$ implies the truth of $S(k)$, then $S(k)$ holds for all integers $k \geq k_0$. This is equivalent to the *minimum principle*: A nonempty set of integers bounded below contains a smallest element.

Let f be a complex-valued function with domain D , and let q be a function on D such that $g(x) > 0$ for all $x \in D$. We write $f \ll g$ or $f = O(g)$ if there exists a constant $c > 0$ such that $|f(x)| \leq cg(x)$ for all $x \in D$. Similarly, we write $f \gg q$ if there exists a constant $c > 0$ such that $|f(x)| \geq c g(x)$ for all $x \in D$. For example, $f \gg 1$ means that $f(x)$ is uniformly bounded away from 0, that is, there exists a constant $c > 0$ such that $|f(x)| \ge c$ for all $x \in D$. We write $f \ll_{k,\ell,\dots} g$ if there exists a positive constant c that depends on the variables k, ℓ, \ldots such that $|f(x)| \leq c g(x)$ for all $x \in D$. We define $f \gg_{k,\ell,...,g} g$ similarly. The functions f and g are called *asymptotic* as x approaches a if $\lim_{x\to a} f(x)/g(x)=1$. Positive-valued functions f and g with domain D have the same *order of magnitude* if $f \ll g \ll f$, or equivalently, if there exist positive constants c_1 and c_2 such that $c_1 \leq f(x)/g(x) \leq c_2$ for all $x \in D$. The *counting function* of a set A of integers counts the number of positive integers in A that do not exceed x , that is,

$$
A(x) = \sum_{\substack{a \in A \\ 1 \le a \le x}} 1.
$$

Using the counting function, we can associate various densities to the set A. The *Shnirel'man density* of A is

$$
\sigma(A) = \inf_{n \to \infty} \frac{A(n)}{n}.
$$

The *lower asymptotic density* of A is

$$
d_L(A) = \liminf_{n \to \infty} \frac{A(n)}{n}.
$$

The *upper asymptotic density* of A is

$$
d_U(A) = \limsup_{n \to \infty} \frac{A(n)}{n}.
$$

If $d_L(A) = d_U(A)$, then $d(A) = d_L(A)$ is called the *asymptotic density* of A, and

$$
d(A) = \lim_{n \to \infty} \frac{A(n)}{n}.
$$

Let A and B be nonempty sets of integers and $d \in \mathbb{Z}$. We define the *sumset*

$$
A + B = \{a + b : a \in A, b \in B\},\
$$

the *difference set*

$$
A - B = \{a - b : a \in A, b \in B\},\
$$

the *product set*

$$
AB = \{ab : a \in A, b \in B\},\
$$

and the *dilation*

$$
d * A = \{d\}A = \{da : a \in A\}.
$$

The sets A and B *eventually coincide*, denoted by $A \sim B$, if there exists an integer n_0 such that $n \in A$ if and only if $n \in B$ for all $n \geq n_0$.

We use the following arithmetic functions:

group of units of R. A commutative ring R is a field if and only if R^{\times} = $R \setminus \{0\}$. If $f(t)$ is a polynomial with coefficients in the ring R, then $N_0(f)$ denotes the number of distinct zeros of $f(t)$ in R. We denote by $M_n(R)$ the ring of $n \times n$ matrices with coefficients in R.

In the study of Liouville's method, we use the symbol

$$
\{f(\ell)\}_{n=\ell^2} = \begin{cases} 0 & \text{if } n \text{ is not a square,} \\ f(\ell) & \text{if } n=\ell^2, \ell \ge 0. \end{cases}
$$

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