Convexity

ROGER WEBSTER

Department of Pure Mathematics, Sheffield University

Oxford New York Tokyo
OXFORD UNIVERSITY PRESS
1994

Contents

In	troduc	ction	xv
1	The	Euclidean space ℝ*	1
	1.1	The Euclidean space ℝ*	1
	1.2		4
	1.3	Dimension	10
	1.4	Hyperplanes	17
		Affine transformations	22
	1.6	Length, distance, and angle	25
	1.7		32
	1.8		38
	1.9	Continuity	43
2	Convex sets		49
	2.1	Basic properties of convex sets	49
	2.2	The convex hull	54
		Interiors and closures	61
	2.4	Separation and support	65
	2.5	Unbounded convex sets	73
	2.6	Facial structure	79
	2.7	The Blaschke selection principle	90
	2.8	Duality	99
3	Convex polytopes		105
	3.1	Polytopes	105
		Polyhedral sets	110
		Pyramids, bipyramids, and prisms	115
	3.4	Cyclic polytopes	120
	3.5	Euler's relation	127
	3.6	Gale transforms	135
4	Linear programming		145
	4.1	The finite basis theorem	145
	4.2	Linear inequalities	149
		Linear programming	156
	4.4	Basic solutions of linear equations	163

Content

	4.5	The simplex algorithm	168
		Game theory	181
5	Co	nvex functions	193
	5.1	Convex functions on the real line	193
	5.2	Classical inequalities	200
	5.3	The gamma and beta functions	206
	5.4	Convex functions on R*	217
	5.5	Continuity and differentiability of convex functions	224
	5.6	Support functions	231
	5.7	The convex programming problem	239
	5.8	Matrix inequalities	244
6	Mixed volumes and extremum problems		
	6.1	Elementary sets	254
	6.2		262
	6.3	The determination of volume	273
	6.4	Mixed volumes and surface area	281
	6.5	The Brunn-Minkowski theorem	297
	6.6	Steiner symmetrization	306
7	Selected topics		
	7.1	Helly's theorem	316
	7.2	Join spaces	330
	7.3	Convexity-preserving mappings	343
	7.4	The geometry of numbers	350
	7.5	Brouwer's fixed-point theorem	356
	7.6	Convex bodies of constant width	367
8	Sol	utions to exercises	377
9	Notes on further reading		425
	Bibliography		431
	Index of symbols and notation		437
	General index		440