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Lie Semigroups and their Applications

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Introduction

Although semigroups of transformations appear already in the original work of S. Lie as part of his efforts to find the right analogue of the theory of substitutions in the context of differential equations, it was Ch. Loewner who first studied such objects purposely [Loe88]. He considered semigroups of self-maps of the unit disc as a tool in geometric function theory. In the late seventies, subsemigroups of Lie groups were considered in relation to control systems with symmetries (cf. [JK81a,b], [Su72]). At about the same time Ol'shanskii introduced such semigroups to in-order to study the representation theory of infinite dimensional classical groups ([Ols91]). Moreover causality questions led people in relativity theory to consider subsemigroups of Lie groups generated by one-parameter semigroups as well. Motivated by this evidence Hofmann and Lawson worked out, in [HoLa83], systematic groundwork for a Lie theory of semigroups. These efforts eventually resulted in the monograph [HHL89].

In the meantime it has become increasingly clear that certain subsemigroups of Lie groups play a vital role in the harmonic analysis of symmetric spaces and representation theory. The purpose of this book is to lead the reader up to these applications of Lie semigroup theory. It is intended for a reader familiar with basic Lie theory but not having any experience with semigroups. In order to keep the overlap with [HHL89] to a minimum we have occasionally quoted theorems without proof from this book – especially when the version there is still the best available. On the other hand the last few years have seen rapid development, and so we are able to present improved versions of many results from [HHL89] with completely new proofs.

This book is not meant to be comprehensive. We have left out various topics that belong to the theory but, at the time being, don't show close connections with the applications we have in mind. Also we have chosen to focus on closed subsemigroups of Lie groups and thereby avoid certain technical complications.

A Lie semigroup is a closed subsemigroup S of a Lie group G which, as a closed subsemigroup, is generated by the images of all the one-parameter semigroups

$$\gamma_X : \mathbb{R}^+ \rightarrow S, \quad t \mapsto \exp(tX).$$

The set of all these one-parameter semigroups can be viewed as a set $\mathbf{L}(S)$ in the Lie algebra \mathfrak{g} of G . It is a closed convex cone satisfying

$$e^{\text{ad } X} \mathbf{L}(S) = \mathbf{L}(S) \quad \forall X \in \mathbf{L}(S) \cap -\mathbf{L}(S),$$

an algebraic identity which reflects the fact that S is invariant under conjugation by elements from the unit group $S \cap S^{-1}$. Convex cones satisfying these properties are called Lie wedges and play the role of Lie algebras in the Lie theory of semigroups. Following the general scheme of Lie theory one wants to study the properties of Lie semigroups via their Lie wedges using the exponential function for the translation mechanism. In Chapter 1 we describe the essential features of this mechanism. In

particular the topological and algebraic obstructions that arise when one tries to find a Lie semigroup with prescribed Lie wedge are pointed out. The problem, called the globality problem, has not been solved in a definitive way, but one has far-reaching results which essentially reduce the globality problem to finding the maximal subsemigroups of Lie groups. The topic of maximal subsemigroups is taken up again later in the book (Chapter 6 and Chapter 8).

The main result of Chapter 1 is Theorem 1.35 which characterizes the Lie wedges that occur as the tangent wedge of a Lie semigroup in terms of the existence of certain functions on the group G . In order to prove it we use a result about ordered homogeneous spaces which is presented only later, in Chapter 4 (Cor. 4.22). We chose this way of organizing things to be able to present the globality problem without too much technical ballast. Moreover the material about ordered homogeneous spaces presented in Chapter 4 is of independent interest even though the separation between semigroup and ordered space aspects may seem artificial to insiders.

Chapter 2 is completely devoted to a list of examples which either have model character or serve as counterexamples at some point. In Chapter 3 we present various geometric and topological properties. Most importantly, it is shown that the interior of a Lie semigroup S is dense if $\mathbf{L}(S)$ generates \mathfrak{g} as a Lie algebra (cf. Theorem 3.8). Also important for later applications is the fact that Lie semigroups admit simply connected covering semigroups (cf. Theorem 3.14).

In Chapter 5 some more consequences of the theory of ordered homogeneous spaces are listed. Among other things it is shown that the unit group of a Lie semigroup is connected. Moreover we explain how the existence of a Lie semigroup with prescribed Lie wedge in a given connected Lie group G is related to the existence of such a Lie semigroup in a covering group of G .

Chapter 6 deals with the characterization of maximal subsemigroups with interior points in simply connected groups with cocompact radical. They all have half-spaces as tangent wedges and a closed subgroup of codimension one as unit group. Finally we show how one can use this result to solve some controllability questions on reductive groups.

The main result of Chapter 7 is Lawson's Theorem on Ol'shanskii semigroups which in particular says that for a connected Lie group G sitting inside a complexification $G_{\mathbb{C}}$ with a Lie algebra \mathfrak{g} which admits a pointed $\text{Ad}(G)$ -invariant cone W with interior points, then $(g, X) \rightarrow g \exp iX$ is a homeomorphism $G \times W \rightarrow G \exp iW$ onto a closed subsemigroup of $G_{\mathbb{C}}$. This semigroup is called a complex Ol'shanskii semigroup. Before we get there we show what consequences the existence of invariant cones with interior points has for a Lie algebra \mathfrak{g} , give a characterization of those Lie algebras containing pointed generating invariant cones, and describe the complete classification of such cones.

Complex Ol'shanskii semigroups and their real analogues appear in many different contexts. They consist of the elements of $G_{\mathbb{C}}$ which map the positive part of the ordered homogeneous space $G_{\mathbb{C}}/G$ into itself, where the ordering is induced by the invariant cone field associated to the invariant cone. In the semisimple case they (at least the ones coming with the maximal invariant cones) can also be viewed as semigroups of compressions

$$\text{compr}(\mathcal{O}) = \{g \in G_{\mathbb{C}} : g \cdot \mathcal{O} \subseteq \mathcal{O}\}$$

of certain open G -orbits \mathcal{O} in suitable flag manifolds associated with $G_{\mathbb{C}}$. In order to show this we study the open G -orbits on complex flag manifolds via the symplectic (in fact, pseudo-Kähler) structure that is given on these orbits. Using the results obtained in this process one can eventually show that complex Ol'shanskiĭ semigroups for maximal invariant cones are maximal subsemigroups.

Apart from their different geometric realizations, complex Ol'shanskiĭ semigroups occur as the natural domains in $G_{\mathbb{C}}$ to which one can analytically continue highest weight representations of G . We show in Chapter 9 how this is done for general G . Moreover we give some examples of this continuation procedure such as the holomorphic discrete series representations and the metaplectic representation which gives rise to Howe's oscillator semigroup. The largest subrepresentation of $L^2(G)$ - for general G - which admits an analytic continuation to a complex Ol'shanskiĭ semigroup leads to a Hardy space of holomorphic functions on this semigroup satisfying an L^2 -condition on G -cosets. This Hardy space coincides with the classical notions for tube domains and polydiscs if G is a vector group or a torus.

In Chapter 10 we collect the results presented in this book for semigroups related to $\mathrm{Sl}(2)$.

For the orientation of the reader we conclude this introduction with some comments on the overlap with [HHL89].

Apart from some elementary properties of Lie wedges and cones Chapter 1 is independent of [HHL89]. The idea of monotone functions is only briefly touched in [HHL89] and the corresponding results we present in Chapter 1 are stronger and the proofs less complicated.

Some of the characteristic examples such as 2.1, parts of 2.2, 2.9 - 2.11 described in Chapter 2 occur also in [HHL89]. We have included them for the convenience of the reader since they illuminate some specific features of the theory.

Chapter 3 is independent of [HHL89]. The results of Section 3.2 were known at that time, but the new proof of Hofmann and Ruppert is shorter and it offers some new insights.

Ordered homogeneous spaces do also occur in [HHL89], where they are used to obtain the results about the structure of Lie semigroups near their group of units (cf. Sections 4.2, 4.3). The results on the global structure of ordered homogeneous spaces concerning properties such as global hyperbolicity are new (cf. Sections 4.4, 4.7).

The *Unit Group Theorem* and the *Unit Neighborhood Theorem* (cf. Section 5.1) were already proved in [HHL89]. Here we obtain these results out of a general theory of ordered homogeneous spaces.

Sections 6.2 - 6.6 are more or less contained in [HHL89]. The results in Sections 6.1 and 6.7 are new and complement the existing results in an interesting way. Since the area of maximal subsemigroups, in particular of maximal subsemigroups in simple groups, still presents many open problems, we decided to include the whole state of the theory of maximal semigroups in Chapter 6. We note also that the Sections 8.1 and 8.6 contain recent results on maximal subsemigroups in semisimple Lie groups complementing the material in Chapter 6 which is mostly concerned with groups G , where $\mathbf{L}(G)$ contains a compact Levi algebra.

Even though the theory of invariant cones and their classification by intersections with compactly embedded Cartan algebras is contained in [HHL89], our

Section 7.1 does not significantly overlap with [HHL89]. Our approach to invariant cones is based on coadjoint orbits. It seems to be more fruitful and far-reaching than the direct approach. Those results on invariant cones which we need in the sequel are proved along these lines. This made it possible to shorten some of the proofs considerably.

The remainder of Sections 7 – 9 is absolutely independent of [HHL89]. For more recent results lying already beyond the scope of this book and concerning the material contained in these sections we refer the reader to [Ne93a-f].

User's Guide

Since many results in this book do not depend on every preceding chapter, we give a list containing for each section, the set of all other sections on which it depends. If, e.g., Section 4.5 depends on Section 4.4 and Section 4.4 depends on Section 4.3, then Section 4.3 appears only in the list of Section 4.4. So the reader has to trace back the whole tree of references by using the lists of several sections. Nevertheless we hope that this is helpful to those readers interested merely in some specific sections of the book.

Chapter 1:

1.2 [1.1], 1.3 [1.1], 1.4 [1.3], 1.8 [1.7], 1.9 [1.1, 1.8], 1.10 [1.4, 1.9]

Chapter 2:

2.3 [1.7], 2.6 [1.4, 1.5, 1.9], 2.7 [1.10]

Chapter 3:

3.1 [1.5, 1.10, 2.2, 2.7], 3.3 [1.10, 2.11], 3.4 [1.10, 3.2], 3.5 [3.4], 3.6 [3.5]

Chapter 4:

4.2 [1.9, 4.1], 4.3 [1.4, 1.9, 4.1, 4.2], 4.4 [1.7, 4.3], 4.5 [4.3], 4.6 [3.2, 4.3], 4.7 [4.4, 4.6]

Chapter 5:

5.1 [1.4, 1.8, 4.3], 5.2 [1.10, 3.2, 4.3, 5.1], 5.3 [3.2, 4.4, 5.1], 5.4 [3.1, 4.2, 5.3], 5.5 [2.5, 5.4]

Chapter 6:

6.2 [2.9], 6.3 [1.7, 6.2], 6.4 [6.3], 6.5 [6.3], 6.6 [6.5], 6.7 [1.2, 1.10, 3.2, 4.2, 4.3, 6.6]

Chapter 7:

7.1 [1.2], 7.2 [1.3, 7.1], 7.3 [4.2, 5.3, 7.2]

Chapter 8:

8.1 [1.7], 8.4 [1.3, 1.7, 7.2, 8.1, 8.3], 8.5 [2.6, 7.2], 8.6 [6.7, 8.4, 8.5]

Chapter 9:

9.3 [3.4, 7.3], 9.4 [8.4], 9.5 [7.1], 9.7 [7.3]