# Grundlehren der mathematischen Wissenschaften 236

A Series of Comprehensive Studies in Mathematics

### **Editors**

S. S. Chern J. L. Doob J. Douglas, jr.

A. Grothendieck E. Heinz F. Hirzebruch E. Hopf

S. Mac Lane W. Magnus M. M. Postnikov

W. Schmidt D. S. Scott

K. Stein J. Tits B. L. van der Waerden

# Managing Editors

B. Eckmann J. K. Moser

# H. Grauert R. Remmert

# Theory of Stein Spaces

Translated by Alan Huckleberry



Springer Science+Business Media, LLC

Hans Grauert Mathematisches Institut der Universität Göttingen D-3400 Göttingen Federal Republic of Germany

Reinhold Remmert Mathematisches Institut der Westfälischen Wilhelms-Universität D-4400 Münster Federal Republic of Germany

Translator: Alan Huckleberry Department of Mathematics University of Notre Dame Notre Dame, Indiana 46556 USA

AMS Subject Classifications: 30A46, 32E10, 32J99, 32-02, 32A10, 32A20, 32C15

#### With 5 Figures

Library of Congress Cataloging in Publication Data Grauert, Hans, 1930-

Theory of Stein spaces.

(Grundlehren der mathematischen Wissenschaften: 236)

Translation of Theorie der Steinschen Räume. Includes index.

1. Stein spaces. I. Remmert, Reinhold, joint author. II. Title. III. Series: Grundlehren der mathematischen Wissenschaften in Einzeldarstellungen;

QA331.G68313

515'.73

79-1430

All rights reserved.

No part of this book may be translated or reproduced in any form without written permission from Springer-Verlag.

© 1979 by Springer Science+Business Media New York Originally published by Springer Berlin Heidelberg New York in 1979 Softcover reprint of the hardcover 1st edition 1979

987654321

ISBN 978-1-4757-4359-3 ISBN 978-1-4757-4357-9 (eBook) DOI 10.1007/978-1-4757-4357-9



# Contents

Intr	oduction	٠	•	٠	•	٠	•	•	•	•	٠	•	•	•	٠	•	•	XV
Cha	pter A. Sheaf Theory																	
§ 0.	Sheaves and Presheaves																	1
	1. Sheaves and Sheaf Mappings																	1
	2. Sums of Sheaves, Subsheaves, and Restriction	ns																1
	3. Sections																	2
	3. Sections																	2
	5. Going from Presheaves to Sheaves. The Fund	cto	r Ť	•														3
	6. The Sheaf Conditions $\mathcal{G}1$ and $\mathcal{G}2$																	3
	7. Direct Products																	4
	8. Image Sheaves																	4
	9. Gluing Sheaves																	5
§ 1.	Sheaves with Algebraic Structure																	5
	1. Sheaves of Groups, Rings, and R-Modules																	5
	2. Sheaf Homomorphisms and Subsheaves .																	6
	3. Quotient Sheaves																	7
	4. Sheaves of Local k-Algebras																	8
	5. Algebraic Reduction																	8
	6. Presheaves with Algebraic Structure																	9
	7. On the Exactness of $\check{\Gamma}$ and $\Gamma$																	9
8 2	Coherent Sheaves and Coherent Functors .																	10
y 2.	1. Finite Sheaves																	10
	2. Finite Relation Sheaves																	11
	3. Coherent Sheaves						-	-				-		-				11
	4. Coherence of Trivial Extensions															•	•	12
	5. The Functors $\bigoplus^p$ and $\bigwedge^p$																	12
	6. The Functor <i>Hom</i> and Annihilator Sheaves														Ċ			13
	7. Sheaves of Quotients																	14
6 2	Complex Spaces																	14
g 3.																		15
	<ol> <li>k-Algebraized Spaces</li> <li>Differentiable and Complex Manifolds</li> </ol>																	
																		15
	3. Complex Spaces and Holomorphic Maps .																	16
	4. Topological Properties of Complex Spaces																	18
	5. Analytic Sets																	18
	6. Dimension Theory																	19
	7. Reduction of Complex Spaces	•	٠	٠	٠	•		•	•	•	•	•	•		•	•	•	
	8. Normal Complex Spaces																	21

§ 4.	Soft and Flabby Sheaves			•	•	•					23 25
Cha	pter B. Cohomology Theory										
§ 1	1. Cohomology Theory 2. Flabby Cohomology Theory 3. The Formal de Rham Lemma										28 30
§ 2	<ol> <li>Čech Cohomology</li> <li>Čech Complexes</li> <li>Alternating Čech Complexes</li> <li>Refinements and the Čech Cohomology Modules H</li></ol>				 						34 35 35 37 37
§ 3	. The Leray Theorem and the Isomorphism Theorems	•	•	•				•	•	•	40 42 43
Ch	apter I. Coherence Theory for Finite Holomorphic Maps										
§ 1	'Finite Maps and Image Sheaves										45
	2. The Bijection $f_*(\mathcal{S})_y \to \prod_{j=1}^t \mathcal{S}_{x_i}$						•				46 47
	5. The $\mathcal{O}_y$ -Module Isomorphism $\check{f}: f_*(\mathcal{S})_y \to \prod_{i=1}^{t} \mathcal{S}_{x_i}$						•	•			48
§ 2	<ol> <li>The General Weierstrass Division Theorem and the Weierstrass</li> <li>Continuity of Roots</li> <li>The General Weierstrass Division Theorem</li> <li>The Weierstrass Homomorphism 𝒪<sup>b</sup> ≃ π<sub>*</sub>(𝒪<sub>A</sub>)</li> <li>The Coherence of the Direct Image Functor π<sub>*</sub></li> </ol>				•	•	•				50
§ 3	The Coherence Theorem for Finite Holomorphic Maps  1. The Projection Theorem  2. Finite Holomorphic Maps (Local Case)  3. Finite Holomorphic Maps and Coherence										52 52 53 54

Contents

Chap	pter II. Differential Forms and Dolbeault Theory	
δ 1.	Complex Valued Differential Forms on Differentiable Manifolds	56
Ü	1. Tangent Vectors	
	2. Vector Fields	
	3. Complex <i>r</i> -vectors	59
	4. Lifting <i>r</i> -vectors	
	5. Complex Valued Differential Forms	
	6. Exterior Derivative	
	7. Lifting Differential Forms	62
	8. The de Rham Cohomology Groups	
§ 2.	Differential Forms on Complex Manifolds	64
	1. The Sheaves $\mathscr{A}^{1,0}$ , $\mathscr{A}^{0,1}$ and $\Omega^1$	
	2. The Sheaves $\mathcal{A}^{p,q}$ and $\Omega^p$	66
	3. The Derivatives $\partial$ and $\overline{\partial}$	67
	4. Holomorphic Liftings of (p, q)-forms	70
6 2	The Lemma of Grothendieck	71
g <i>3</i> .	1. Area Integrals and the Operator T	/1
	2. The Commutivity of T with Partial Differentiation	
	2. The Commutatory of T with Partial Differentiation $(\partial \bar{z})(Tf) = f$	
	4. A Lemma of Grothendieck	
§ 4.	Dolbeault Cohomology Theory	77
-	1. The Solution of the $\bar{\partial}$ -problem for Compact Product Sets	77
	2. The Dolbeault Cohomology Groups	79
	3. The Analytic de Rham Theory	
Supp	plement to Section 4.1. A Theorem of Hartogs	81
Chaj	apter III. Theorems A and B for Compact Blocks $\mathbb{C}^m$	
8 1	The Attaching Lemmas of Cousin and Cartan	83
3 1.	1. The Lemma of Cousin	
	2. Bounded Holomorphic Matrices	
	3. The Lemma of Cartan	
8 2	Attaching Sheaf Epimorphisms	89
y 2.	1. An Approximation Theorem of Runge	90
	2. The Attaching Lemma for Epimorphisms of Sheaves	92
§ 3.	Theorems A and B	95
	1. Coherent Analytic Sheaves on Compact Blocks	96
	2. The Formulations of Theorems A and B and the Reduction of Theorem B to	Theorem A 96
	3. The Proof of Theorem A for Compact Blocks	98
Cha	apter IV. Stein Spaces	
§ 1.	<ol> <li>The Vanishing Theorem H<sup>q</sup>(X, S) = 0</li> <li>Stein Sets and Consequences of Theorem B</li> <li>Construction of Compact Stein Sets Using the Coherence Theorem for Finite</li> </ol>	100
	2. Constitution of Compact Stem Sets Compact the Concrene Theorem for Time	, 1410ths 101

X	Contents

	3. Exhaustions of Complex Spaces by Compact Stein Sets							. 102
	4. The Equations $H^q(H, \mathcal{S}) = 0$ for $q \ge 2$							. 103
	5. Stein Exhaustions and the Equation $H^1(X, \mathcal{S}) = 0$							. 104
8 2	Weak Holomorphic Convexity and Stones							108
3	1. The Holomorphically Convex Hull	•	•	•	•		•	100
	2. Holomorphically Convey Spaces	•	•	•	•		٠	. 100
	2. Holomorphically Convex Spaces	٠	•	•	•		٠	. 109
	3. Stones	٠	•	•			٠	. 111
	4. Exhaustions by Stones and Weakly Holomorphically Convex Space	es						. 112
	5. Holomorphic Convexity and Unbounded Holomorphic Functions							. 113
§ 3.	Holomorphically Complete Spaces							116
3	1. Analytic Blocks							
	2. Holomorphically Spreadable Spaces	•	•	•	•		•	. 110
	2. Holomorphically Convey Spaces	•	•	•	•		٠	. 11/
	3. Holomorphically Convex Spaces	•	•	•	•		•	. 11/
§ 4.	Exhaustions by Analytic Blocks are Stein Exhaustions							. 118
	1. Good Semi-norms							. 118
	2. The Compatibility Theorem							. 119
	3. The Convergence Theorem							, 120
	4. The Approximation Theorem							
	5. Exhaustions by Analytic Blocks are Stein Exhaustions	•	·	•	•	• •	•	123
	2	•	•	•	•	• •	•	. 123
Cha	pter V. Applications of Theorems A and B							
§ 1.	Examples of Stein Spaces							. 125
	1. Standard Constructions							. 125
	2. Stein Coverings							
	3. Differences of Complex Spaces							. 128
	4. The Spaces $\mathbb{C}^2\setminus\{0\}$ and $\mathbb{C}^3\setminus\{0\}$							. 130
	5. Classical Examples							
	6. Stein Groups							
	or promotoupour and a second s	•	•	•	•	•	•	. 150
§ 2.	The Cousin Problems and the Poincaré Problem							
	1. The Cousin I Problem							. 136
	2. The Cousin II Problem							. 138
	3. Poincaré Problem							. 139
	4. The Exact Exponential Sequence $0 \to \mathbb{Z} \to \mathcal{O} \to \mathcal{O}^* \to 1$							. 142
	5. Oka's Principle							
§ 3.	Divisor Classes and Locally Free Analytic Sheaves of Rank 1	•	٠	•				
	1. Divisors and Locally-Free Sheaves of Rank 1		•	•				. 146
	2. The Isomorphism $H^1(X, \mathcal{O}^*) \to LF(X)$							. 147
	3. The Group of Divisor Classes on a Stein Space							. 148
g 4	Shoof Theoretical Characterization of Stain Spaces							150
9 4.	Sheaf Theoretical Characterization of Stein Spaces							
	1. Cycles and Global Holomorphic Functions							
	2. Equivalent Criteria for a Stein Space							
	3. The Reduction Theorem							
	4. Differential Forms on Stein Manifolds							
	5. Topological Properties of Stein Spaces							. 156

Contents	ΚI
ontents X	(I

§	5.	A Sheaf Theoretical Characterizati	on (	of S	Stei	n I	Oor	na	ins	in	$\mathbb{C}^m$												157
		1. An Induction Principle																					157
		2. The Equations $H^1(B, \mathcal{O}_R) = \cdots$	= H	m –	1 (B	3. O	R)	= (	0														159
		3. Representation of 1			`.	٠.	٠,																161
		4. The Character Theorem									_												162
				•				·		·		•			•	·		٠		•	·	•	
8	6.	The Topology on the Module of So	ectio	ons	of	a (	Col	ier	ent	Sh	eaf	•											163
J		0. Fréchet Spaces																					
		1. The Topology of Compact Con-																					
		2. The Uniqueness Theorem																					
		3. The Existence Theorem	•	•	•	•	•	•	•	•	•	•	•	•	٠	٠	•	•	•	٠	•	•	166
		4. Properties of the Canonical Top	Molo	ov.	•	٠	٠	•	•	•	•	•	•	•	•	•	•	٠	•	•	•	٠	168
		5. The topologies for $C^q(\mathfrak{U}, \mathcal{S})$ and	1 79	(B)	i	١.	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	170
		6. Reduced Complex Spaces and C	'\	ιω,	at C	) }		•			•	٠	•	•	•	•	•	•	•	•	•	•	170
		7. Convergent Series																					
		7. Convergent Series	•	•	•	٠	٠	•	•	•	•	•	•	•	•	٠	٠	•	•	٠	٠	٠	1/1
e	7	Character Theory for Stein Algebra																					176
8	/٠	1. Characters and Character Ideals	13	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	176
		2. Finiteness Lemma for Character	. T.J.	1 .		•	•	•	•	•	•	•	•	•	•	٠	•	•	•	•	•	٠	170
		3. The Homeomorphism $\Xi: X \to \mathcal{X}$	(I)	)	٠	•	٠	٠	٠	•	٠	٠	٠	٠	•	٠	٠	•	٠	٠	٠	٠	180
		4. Complex Analytic Structure on	A (I	)	٠	•	٠	٠	٠	•	•	•	٠	•	•	•	٠	•	٠	٠	٠	٠	181
		oter VI. The Finiteness Theorem  Square-integrable Holomorphic Fu	ın at																				107
8	1.																						
		1. The Space $\mathcal{O}_h(B)$																					
		2. The Bergman Inequality																					
		3. The Hilbert Space $\mathcal{O}_h^k(B)$																					
		4. Saturated Sets and the Minimur																					
		5. The Schwarz Lemma	٠	٠	•	٠	٠	٠	٠	٠	٠	٠	٠	•	٠	٠	٠	٠	٠	•	•	•	190
8	2	Monotone Orthogonal Bases																					101
8	۷.	1. Monotonicity																					
		2. The Subdegree																					
		3. Construction of Monotone On																					
		5. Construction of Monotone Of	tiit	go.	ııaı	ט	asc	.3	υy	141	cai	13	OI	141	1111	1111		ı uı	ici	101	13	•	193
Ş	3.	Resolution Atlases																					194
•		1. Existence																					
		2. The Hilbert Space $C_{\mathbf{k}}^{\mathbf{q}}(\mathfrak{U}, \mathscr{S})$ .																					
		3. The Hilbert Space $Z_{k}^{n}(\mathfrak{U}, \mathscr{S})$ .																				i	197
		4. Refinements																					
			-			-						•				Ť		•	·	•	•	•	
Ş	4.	The Proof of the Finiteness Theore	m																				200
0		1. The Smoothing Lemma																•	·	•			200
		2. Finiteness Lemma				•	•	•	•	•	•	•	•	•	•	•	٠	•	•			-	201
		3. Proof of the Finiteness Theorem				•	•	•	•	•	•	•		•	•	•	•	•	•				201 202
		2. 11301 of the 1 inteness Theorem	٠.	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	202
C	haj	oter VII. Compact Riemann Surface	es																				
8	1.	Divisors and Locally Free Sheaves																					204
J		0. Divisors										•	•	•	•	•	•	•	•	•			205
		1. Divisors of Meromorphic Section				•	•	•	•	٠	•	•	•	•	•	•	•	•	•	•			205
		1. Divisors of Micromorphic Section	113	•	•	•	•	٠	•	٠	•	•	٠	•	•	•	•	•	•	٠	•	•	دںے

	2. The Sheaves $\mathcal{F}(D)$	. 206
	3. The Sheaves $\mathcal{O}(D)$	
	( )	
8 2	The Existence of Global Meromorphic Sections	200
9 2	1 The Common O \(\pi(D)\) \(\pi(D)\)	. 200
	1. The Sequence $0 \to \mathcal{F}(D) \to \mathcal{F}(D') \to \mathcal{F} \to 0$	
	2. The Characteristic Theorem and the Existence Theorem	
	3. The Vanishing Theorem	. 210
	4. The Degree Equation	. 210
	min' n'ana (n'i v')	244
§ 3	The Riemann-Roch Theorem (Preliminary Version)	
	1. The Genus of Riemann-Roch	
	2. Applications	. 212
8 4	The Structure of Locally Free Sheaves	213
8 7	·	
	1. Locally Free Subsheaves	
	2. The Existence of Locally Free Subsheaves	
	3. The Canonical Divisors	. 214
Suj	oplement to Section 4. The Riemann-Roch Theorem for Locally Free Sheaves	
	1. The Chern Function	. 215
	2. Properties of the Chern Function	216
	3. The Riemann-Roch Theorem	
§ 5	. The Equation $H^1(X, \mathcal{M})$	
	1. The C-homomorphism $\mathcal{O}(np)(X) \to \operatorname{Hom}(H^1(X, \mathcal{O}(D)), H^1(X, \mathcal{O}(D+np)))$	
	2. The Equation $H^1(X, \mathcal{O}(D+np))=0$	. 218
	3. The Equation $H^1(X, \mathcal{M}) = 0$	
§ 6	. The Duality Theorem of Serre	. 219
	1. The Principal Part Distributions with Respect to a Divisor	. 219
	2. The Equation $H^1(X, \mathcal{O}(D)) = I(D)$	. 220
	3. Linear Forms	
	4. The Inequality $\operatorname{Dim}_{\mathcal{M}(X)} J \leq 1$	
	5. The Residue Calculus	
	6. The Duality Theorem	
	o. The Duality Theorem	. 223
8 7	The Riemann-Roch Theorem (Final Version)	. 225
§ 7	The Riemann-Roch Theorem (Final Version)  1. The Equation $i(D) = l(K - D)$	
§ 7	1. The Equation $i(D) = l(K - D)$	. 225
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227 . 228
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227 . 228
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227 . 228 . 229
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227 . 228 . 229
§ 7	1. The Equation $i(D) = l(K - D)$	. 225 . 226 . 227 . 227 . 228 . 229
	1. The Equation $i(D) = l(K - D)$ .  2. The Formula of Riemann–Roch  3. Theorem B for Sheaves $\mathcal{O}(D)$ 4. Theorem A for Sheaves $\mathcal{O}(D)$ 5. The Existence of Meromorphic Differential Forms  6. The Gap Theorem  7. Theorems A and B for Locally Free Sheaves  8. The Hodge Decomposition of $H^1(X, \mathbb{C})$	. 225 . 226 . 227 . 227 . 228 . 229 . 231
	1. The Equation $i(D) = l(K - D)$ .  2. The Formula of Riemann-Roch  3. Theorem B for Sheaves $\mathcal{O}(D)$ 4. Theorem A for Sheaves $\mathcal{O}(D)$ 5. The Existence of Meromorphic Differential Forms  6. The Gap Theorem  7. Theorems A and B for Locally Free Sheaves  8. The Hodge Decomposition of $H^1(X, \mathbb{C})$	. 225 . 226 . 227 . 227 . 228 . 229 . 231
	1. The Equation $i(D) = l(K - D)$ .  2. The Formula of Riemann–Roch  3. Theorem B for Sheaves $\mathcal{O}(D)$ 4. Theorem A for Sheaves $\mathcal{O}(D)$ 5. The Existence of Meromorphic Differential Forms  6. The Gap Theorem  7. Theorems A and B for Locally Free Sheaves  8. The Hodge Decomposition of $H^1(X, \mathbb{C})$	. 225 . 226 . 227 . 227 . 228 . 229 . 231 . 232 . 232
	1. The Equation $i(D) = l(K - D)$ .  2. The Formula of Riemann–Roch  3. Theorem B for Sheaves $\mathcal{O}(D)$ 4. Theorem A for Sheaves $\mathcal{O}(D)$ 5. The Existence of Meromorphic Differential Forms  6. The Gap Theorem  7. Theorems A and B for Locally Free Sheaves  8. The Hodge Decomposition of $H^1(X, \mathbb{C})$ The Splitting of Locally Free Sheaves  1. The Number $\mu(\mathcal{F})$ 2. Maximal Subsheaves	. 225 . 226 . 227 . 227 . 228 . 229 . 231 . 232 . 232 . 233
	1. The Equation $i(D) = l(K - D)$ .  2. The Formula of Riemann-Roch  3. Theorem B for Sheaves $\mathcal{O}(D)$ 4. Theorem A for Sheaves $\mathcal{O}(D)$ 5. The Existence of Meromorphic Differential Forms  6. The Gap Theorem  7. Theorems A and B for Locally Free Sheaves  8. The Hodge Decomposition of $H^1(X, \mathbb{C})$ The Splitting of Locally Free Sheaves  1. The Number $\mu(\mathcal{F})$ .	. 225 . 226 . 227 . 227 . 228 . 229 . 231 . 232 . 232 . 233 . 234

Contents	XIII
6. Existence of the Splitting	
Bibliography	 . 240
Subject Index	 . 243
Table of Symbols	 . 248

## Introduction

1. The classical theorem of Mittag-Leffler was generalized to the case of several complex variables by Cousin in 1895. In its one variable version this says that, if one prescribes the principal parts of a meromorphic function on a domain in the complex plane C, then there exists a meromorphic function defined on that domain having exactly those principal parts. Cousin and subsequent authors could only prove the analogous theorem in several variables for certain types of domains (e.g. product domains where each factor is a domain in the complex plane). In fact it turned out that this problem can not be solved on an arbitrary domain in  $\mathbb{C}^m$ ,  $m \ge 2$ . The best known example for this is a "notched" bicylinder in  $\mathbb{C}^2$ . This is obtained by removing the set  $\{(z_1, z_2) \in \mathbb{C}^2 \mid |z_1| \geq \frac{1}{2}, |z_2| \leq \frac{1}{2}\}$ , from the unit bicylinder,  $\Delta := \{(z_1, z_2) \in \mathbb{C}^2 | |z_1| < 1, |z_2| < 1\}$ . This domain *D* has the property that every function holomorphic on D continues to a function holomorphic on the entire bicylinder. Such a phenomenon never occurs in the theory of one complex variable. In fact, given a domain  $G \subset \mathbb{C}$ , there exist functions holomorphic on G which are singular at every boundary point of G. In several complex variables one calls such domains (i.e. domains on which there exist holomorphic functions which are singular at every boundary point) domains of holomorphy. H. Cartan observed in 1934 that every domain in C<sup>2</sup> where the above "Cousin problem" is always solvable is necessarily a domain of holomorphy. A proof of this was communicated by Behnke and Stein in 1937. Meanwhile it was conjectured that Cousin's theorem should hold on any domain of holomorphy. This was in fact proved by Oka in 1937: For every prescription of principal parts on a domain of holomorphy  $D \subset \mathbb{C}^m$ , there exists a meromorphic function on D having exactly those principal parts. In the same year, via the example of  $\mathbb{C}^3\setminus\{0\}$ , H. Cartan showed that it is possible for the Cousin theorem to be valid on domains which are not domains of holomorphy.

As the theory of functions of several complex variables developed, it was often the case that, in order to have a chance of carrying over important one variable results, it was necessary to restrict to domains of holomorphy. This was particularly true with respect to the analog of the Weierstrass product theorem. Formulated as a question, it is as follows: Given a domain D in  $\mathbb{C}^m$ , can one prescribe the zeros (counting multiplicity) of a holomorphic function on D? It was soon realized that in some cases it is impossible to find even a continuous function which does the job. Conditions for the existence of a continuous solution of this

XVI Introduction

problem, the so-called "second Cousin problem," were discussed by K. Stein in 1941. In fact he gave a sufficient condition which could actually be checked in particular examples. Nowadays this is stated in terms of the vanishing of the Chern class of the prescribed zero set. Stein, however, stated this in a dual and more intuitively geometric way. His condition is as follows: The "intersection number" of the zero surface (counting multiplicity) with any 2-cycle in D should always be zero.

It was similarly necessary to restrict to domains of holomorphy in order to prove the appropriate generalizations of the facts that, on a domain in  $\mathbb{C}$ , every meromorphic function is the ratio of (globally defined) analytic functions and, if the domain is simply connected, holomorphic functions can be uniformly approximated by polynomials (i.e. the Runge approximation theorem). Poincaré first posed the question about meromorphic functions of several variables being quotients of globally defined relatively prime holomorphic functions. He in fact answered this positively in certain interesting cases (e.g. for  $\mathbb{C}^m$  itself).

2. It is not at all straightforward to generalize the notion of a Mittag-Leffler distribution (i.e. prescriptions of principal parts) to the several variable case. The main difficulty is that the set on which the desired function is to have poles is no longer discrete. In fact, in the case of domains in  $\mathbb{C}^m$ ,  $m \ge 2$ , this set is a (2m-2)-dimensional real (possibly singular) surface. Thus one can no longer just prescribe points and pieces of Laurent series. This can be circumvented as follows: If G is a domain in  $\mathbb{C}^m$  and  $\mathbb{U} = \{U_i\}$ ,  $i \in I$ , is an open covering of G, then the family  $\{U_i, h_i\}$  is called an additive Cousin distribution on G, whenever each  $h_i$  is a meromorphic function on  $U_i$ , and on  $U_{i_0i_1} := U_{i_0} \cap U_{i_1}$  the difference  $h_{i_0} - h_{i_1}$  is holomorphic for all choices of  $i_0$  and  $i_1$ . In the case of m = 1, this means that  $h_{i_0}$  and  $h_{i_1}$  have the same principal parts. Thus one obtains a Mittag-Leffler distribution from the Cousin distribution. A meromorphic function h is said to have the Cousin distribution for its principal parts if  $h - h_i$  is holomorphic on  $U_i$  for all i.

Different Cousin distributions can, on the same covering, define the same distribution of principal parts. This difficulty is overcome by introducing an equivalence relation. For this let  $x \in G$ . Let U be an open neighborhood of x in G and suppose that h is meromorphic on U. Then the pair (U, h) is called a locally meromorphic function at x. Two such pairs  $(U_1, h_1)$  and  $(U_2, h_2)$  are called equivalent if there exists a neighborhood V of x with  $V \subset U_1 \cap U_2$  and  $h_1 - h_2$  holomorphic on V. Each equivalence class is called a germ of a principal part. The set of all germs of principal parts at x is denoted by  $\mathscr{H}_x$ . We define  $\mathscr{H} := \bigcup_{x \in X} \mathscr{H}_x$  and

denote by  $\pi: \mathcal{H} \to G$  the map which associates to every germ its base point  $x \in G$ . If  $U \subset G$  is open and h is meromorphic on U then, for every  $x \in U$ , one has the associated principal part of h at x,  $\bar{h}_x \in \mathcal{H}_x$ . Consequently there exists a map  $s_h \colon U \to \mathcal{H}$ ,  $x \mapsto \bar{h}_x$ , such that  $\pi \cdot s_h = id$ . It is easy to check that sets of the form  $s_h(U)$ , where U is any open set in G and h is any meromorphic function on U, form a basis for a topology on  $\mathcal{H}$ . Further, in this topology,  $\pi \colon \mathcal{H} \to G$  is seen to be continuous and a local homeomorphism. In such a situation one calls  $\mathcal{H}$  a sheaf over G. The fibers of  $\pi$  should be thought of as stalks with the open sets looking

Introduction XVII

like transversal surfaces given by the maps  $s_h$ . The map  $s_h$ :  $U \to \mathcal{H}$  is called a local section over U. Every Cousin distribution  $\{U_i, h_i\}$  defines a global continuous map (section)  $s: G \to \mathcal{H}$  with  $\pi \cdot s = id$ . This is locally defined by  $s \mid U_i := s_{h_i}$ . The condition that, for all i and j,  $h_i - h_j$  is holomorphic on  $U_i \cap U_j$  is equivalent to the fact that s is well-defined. Two Cousin distributions have the same principal parts if and only if they correspond to the same section in D over G. A meromorphic function h is a "solution" of the Cousin distribution s (i.e. has exactly the same principal parts as were prescribed) exactly when  $s_h = s$ .

It is clear from the above that the sheaf theoretic language is the ideal medium for the statement of the generalization of the Mittag-Leffler problem to the several variable situation. Of course for domains in  $\mathbb{C}^n$  Oka had solved this without explicit use of sheaves. But even in this case the language of sheaves isolated the real problems and made the seemingly complicated techniques of Oka more transparent. This was also true in the case of the second Cousin problem, the Poincaré problem, etc. Furthermore this language was ideal for formulating new problems and for paving the road toward possible obstructions to their solutions. Theorems about sheaves themselves later gave rise to numerous interesting applications.

3. The germs of holomorphic functions form a sheaf which is usually denoted by  $\mathscr{C}$ . It has already been pointed out that the zero sets of analytic functions are important even in the study of the Cousin problems. Thus it should be expected that analytic sets, which are just sets of simultaneous zeros of finitely many holomorphic functions on domains in the various  $\mathbb{C}^m$ , would play an important role in the early development of the theory. In fact the totality of germs of holomorphic functions which vanish on a particular analytic set form a subsheaf of  $\mathscr{C}$  which frequently comes into play in present day complex analysis. In 1950 Oka himself used the idea of distributions of ideals in rings of local holomorphic functions (idéaux de domaines indéterminés). This notion, which at the time of its conception seemed difficult and mysterious, just corresponds to the simple idea of a sheaf of ideals.

The use of germs and the idea of sheaves go back to the work of J. Leray. Sheaves have been systematically applied in the theory of functions of several complex variables ever since 1950/51. The idea of *coherence* is very important for many considerations in several complex variables. Roughly speaking, a sheaf of  $\ell$ -modules is coherent if it is locally free except possibly on some small set where it is still finitely generated with the ring of relations again being finitely generated. Even in the early going it was necessary to prove the coherence of many sheaves. This was often quite difficult, because there were really no techniques around and most work had to be done from scratch. The most important coherence theorems originated with H. Cartan and K. Oka. After the foundations had been laid, coherent sheaves quickly enriched the theory of domains of holomorphy with new important results. In the meantime, in his memorable work "Analytische Functionen mehrerer komplexer Veränderlichen zu vorgegebenen Periodizitätsmoduln und das zweite Cousinsche Problem," Math. Ann. 123(1951), 201-222, K. Stein had discovered complex manifolds which have basic (elementary) properties simi-

XVIII Introduction

lar to domains of holomorphy. A domain  $G \subset \mathbb{C}$  is indeed a domain of holomorphy if and only if it is a *Stein manifold*. The main point is that many theorems about coherent sheaves on domains of holomorphy can as well be proved for Stein manifolds. Cartan and Serre recognized that the language of sheaf cohomology, which had been developed only shortly before, is particularly suitable for the formulation of the main results: For every coherent sheaf  $\mathscr S$  over a Stein manifold X, the following two theorems hold:

**Theorem A.** The  $\mathcal{C}(X)$ -module of global sections  $\mathcal{S}(X)$  generates every stalk  $\mathcal{S}_x$  as an  $\mathcal{C}_x$ -module for all  $x \in X$ .

**Theorem B.**  $H^q(X, \mathcal{S}) = 0$  for all  $q \ge 1$ .

These famous theorems, which were first proved in the Seminaire Cartan 1951/52, contain, among many others, the results pertaining to the Cousin problems.

4. Following the original definition, a paracompact complex manifold is called a Stein manifold if the following three axioms are satisfied:

**Separation Axiom:** Given two distinct points  $x_1, x_2 \in X$ , there exists a function f holomorphic on X such that  $f(x_1) \neq f(x_2)$ .

**Local Coordinates Axiom:** If  $x_0 \in X$  then there exists a neighborhood U of  $x_0$  and functions  $f_1, \ldots, f_m$  which are holomorphic on X such that the restrictions  $z_i := f_i \mid U, i = 1, \ldots, m$ , give local coordinates on U.

**Holomorphic Convexity Axiom:** If  $\{x_i\}$  is a sequence which "goes to  $\infty$  in X" (i.e. the set  $\{x_i\}$  is discrete) then there exists a function f holomorphic on X which is unbounded on  $\{x_i\}$ : sup  $|f(x_i)| = \infty$ .

It is clear that a domain in  $\mathbb{C}^m$  is a Stein manifold if and only if it is holomorphically convex. However if one wants to study non-schlicht domains over  $\mathbb{C}^m$  (i.e. ramified covers of domains in  $\mathbb{C}^m$ ), then it is not apriori clear that two points lying over the same base point can be separated by global holomorphic functions. Likewise it is not obvious that neighborhoods of ramification points have local coordinates which are restrictions of global holomorphic functions. If one allows points which are not locally uniformizable (i.e. points where there is a genuine singularity and the "domain" is not even a manifold, as is the case at the point  $(0, 0, 0) \in V := \{(x, y, z) \in \mathbb{C}^3 \mid x^2 = yz\}$ , which is spread over the (y, z)-plane by projection) then the above definition is meaningless, because we assumed that X is a manifold. However, even in the non-locally uniformizable situation above, the following significant weakening of the separation and local coordinate axioms still holds:

Introduction XIX

**Weak Separation Axiom:** For every point  $x_0 \in X$  there exist functions  $f_1, \ldots, f_n \in \mathcal{C}(X)$  so that  $x_0$  is an isolated point in  $\{x \in X \mid f_1(x) = \cdots = f_n(x) = 0\}$ .

Among other things, this allows the consideration of spaces with singularities. Due to the maximum principle, this weak separation implies that *every compact* analytic subspace of X is finite.

It turns out that, without losing the main results, the convexity axiom can also be somewhat weakened:

**Weak Convexity Axiom:** Let K be a compact set in X and W an open neighborhood of K in X. Then  $\hat{K} \cap W$  is compact, where  $\hat{K}$  denotes the holomorphic hull of K in X:

$$\widehat{K} := \{ x \in X \mid |f(x)| \le \sup_{y \in K} |f(y)|, \text{ for all } f \in \mathcal{C}(X) \}.$$

One way of strengthening the axiom immediately above is to require that  $\hat{K}$  be compact in X. If one does this and further considers only the case where X is a manifold, then, without the use of deep techniques, one can show that the strengthened axiom is equivalent to the holomorphic convexity axiom (see Theorems IV.2.4 and IV.2.12).

For the purposes of this book, a Stein space is a paracompact (not necessarily reduced) complex space for which Theorem B is valid. It is proved that this condition is equivalent to the validity of Theorem A, and is also equivalent to the above weakened axioms. In particular it follows that if X is a manifold, the weakened axioms imply Stein's original axioms.

We will always assume that a complex space has *countable topology* and is thus *paracompact*. With a bit of work one can show that any irreducible complex space which satisfies the weak separation axiom is eo ipso paracompact (see 16, 24).

5. We conclude our introductory remarks with a short description of the contents of this book. We begin with two brief preliminary chapters (Chapters A and B) where we assemble the important information from sheaf theory and the related cohomology theories. The idea of coherence is explained in these chapters. A reader who is really interested in coherence proofs, can find such in our book, "Coherent Analytic Sheaves," which is presently in preparation. Complex spaces are introduced as special C-algebraized spaces. Further we develop cohomology from the point of view of alternating (Čech) cochains as well as via flabby resolutions. Proofs which are easily accessible in the literature (e.g. [SCV], [TF], or [TAG]) are in general not carried out.

In Chapter I a short direct proof of the coherence theorem for finite holomorphic maps is given. It is based primarily on the Weierstrass division theorem and Hensel's lemma for convergent power series.

The Dolbeault cohomology theory is presented in Chapter II. As a consequence we obtain Theorem B for the structure sheaf  $\mathcal{C}$  over a compact euclidean block (i.e. an *m*-fold product of rectangles), K, in  $\mathbb{C}^m$ . In other words, for  $q \geq 1$ ,  $H^q(K, \mathcal{C}) = 0$ . It should be noted that, although we want to introduce Dolbeault

XX Introduction

cohomology in any case, this result follows directly and with less difficulty via the Čech cohomology.

Chapter III contains the proofs for Theorems A and B for coherent sheaves over euclidean blocks  $K \subset \mathbb{C}^m$ . One of the key ingredients for the proofs is the fact that, for every coherent sheaf  $\mathscr{S}$ , the cohomology groups,  $H^q(K, \mathscr{S})$ , vanish for all q large enough. The deciding factor in proving Theorem A is the "Heftungslemma" of Cartan. This is proved quite easily if while solving the Cousin problem, one simultaneously estimates the attaching functions.

In Chapter IV Theorems A and B are proved for an arbitrary Stein space, X. A summary of the proof is the following: First it is shown that X is exhausted by analytic blocks. (An analytic block is a compact set in X which can be mapped by a finite, proper, holomorphic map into an euclidean block in some  $\mathbb{C}^m$ .) The coherence theorem for finite maps along with the results in Chapter III yield the desired theorem free of charge. In order to obtain such theorems in the limit (i.e. for spaces exhausted by analytic blocks), an approximation technique, which is a generalization of the usual Runge idea, is needed.

Applications and illustrations of the main theorems, as well as examples of Stein manifolds, are given in Chapter V. The canonical Fréchet topology on the space of global sections  $\mathcal{S}(X)$  of a coherent analytic sheaf is described in Section 4. By means of the normalization theorem, which we do not prove in this book, we give a simple proof for the fact that, for a reduced complex space X, the canonical Fréchet topology on  $H^0(X, \mathcal{C})$  is the topology of compact convergence.

Chapter VI is devoted to proving that, for a coherent analytic sheaf  $\mathcal S$  on a compact complex space  $X, H^q(X, \mathcal S), q \geq 0$ , are finite dimensional  $\mathbb C$ -vector space (Théorème de finitude of Cartan and Serre). In this proof we work with the Hilbert space of square-integrable holomorphic functions and make use of the orthonormal basis which was introduced by S. Bergman. The classical Schwarz lemma plays an important role, replacing the lemma of L. Schwartz on linear compact maps between Fréchet spaces.

In Chapter VII we attempt to entertain the reader with a presentation of the theory of compact Riemann surfaces which results from, among other considerations, the finiteness theorem of Chapter V. The celebrated Riemann-Roch and Serre duality theorems are proved. The flow of the proof is more or less like that in Serre [35], except that, in the analytic case, a real argument for  $H^1(X, \mathcal{M}) = 0$  is needed. This is done in a simple way using an idea of R. Kiehl. The book closes with a proof of the Grothendieck theorem on the splitting of vector bundles over  $\mathbb{C}P_1$ .

The reader should be advised that, while the English version is not a word for word translation of Theorie der Steinschen Räume, there are no significant changes in the mathematics. There are a number of strategies for reading this book, depending on the experience and viewpoint of the reader. Those who are not currently working the field might first browse through the chapter on applications (Chapter V).

It gives us great pleasure to be able to dedicate this book to Karl Stein, who initiated the theory as well as collaborated in its development. Various prelimin-

Introduction XXI

ary versions of our texts were already in existence in the middle 60's. We would like to thank W. Barth for his help at that time.

It is our pleasure to express sincere thanks to Professor Dr. Alan Huckleberry from the University of Notre Dame, South Bend, Indiana, for translating this book into English.

Göttingen, Münster/Westf.

H. Grauert R. Remmert